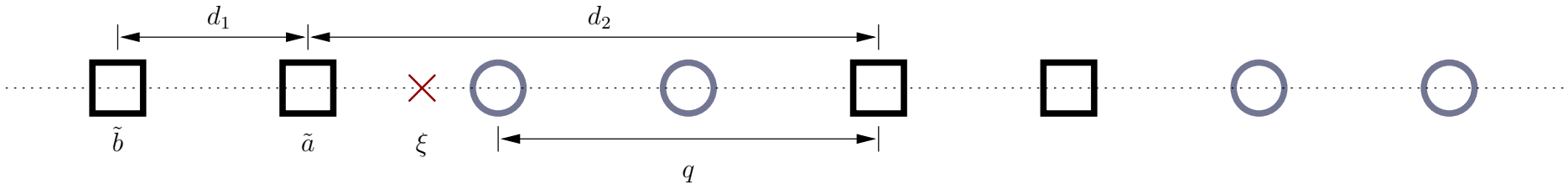
d_1
d_2
$\tilde{b}$
$\tilde{a}$
ξ
q